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Model Median Score* Average Reward Random Policy 3+1-0 0.08 Humany
145+36-38 0.68 No Human Demonstrations, -greedy, $K = 1.5$ 105batches 17+1-8
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MDP, Reinforcement Learning And Apprenticeship Learning Example: Tom And Jerry,
Control Jerry (Jerry's Perspective) • State: The Position Of Tom And Jerry,
 $25*25=625$ In Total; One Of The States . One Of The States . Markov Decision
Process (MDP) ... Run One Step To Obtain . S' ... 3th, 2024 Deep Reinforcement
Learning With Double Q-learning It Is An Open Question Whether, If The
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Bradford Book The MIT Press 4th, 2024 Reinforcement Learning: A Brief
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Cannot Move Outside Of The Grid (i.e. End Up In The Same State) - Agent Is Flung
Randomly To Corner Of Grid After Entering A Goal Or Penalty State • Rewards: -
Attempted Move Outside Of Grid Leads To Reward Of -1 - Go 3th, 2024 Lecture 1:
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