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Model:  $\dot{X}_k = F_k(X_k, u_k)$ ,  $K > I$  Performance Index:  $J = \int_0^T L(X_k, u_k) dt + \Phi(X_T)$  Hamiltonian:  $H = F_k(X_k, u_k) + \lambda^T (F_k(X_k, u_k) - \dot{X}_k)$  — Costate Equation:  $\dot{\lambda} = -\partial L / \partial X_k$  May 1th, 2024

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