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By A Factor Of 2. Note That Every Vector Is A 2-eigenvector. In Other Words, All Of  $\mathbb{R}^2$  Is The 2-eigenspace. Figure 6: Expansion Figure 7: Contraction Figure 8: Half Turn A Scalar Matrix Is A Multiple Of The Identity Matrix Like T Jun 2th, 2024 Linear Algebra: A Modern Introduction Elementary Linear ... Math 2114: Introduction To Linear Algebra Tues/Thurs 2:00pm-3:15pm In McBryde 308 Spring 2020 (CRN Jul 2th, 2024 Chapter 5. Linear Algebra Sections 5.1 - 5.4 Linear ... 18 (a) The System Has A Unique Solution; The Three Planes Have A Unique Point Of Intersection; (b) The System Has Infinitely Many Solutions; The Three Planes Intersect In A Line, Or The Three Planes Intersect In A Plane. ... -3x Jan 2th, 2024.

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