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X State Step Response X 1 X 2 0 0.5 1 1.5 2 2.5 3 3.5 4 -15 -10 -5 0 5 Time (sec)
U Control Step Response: $U = \bar{N} R - K_x U = \bar{N} R - K_x$ Figure 3: Response To Step Input With The N^- Correction. Gives The Desired Steady- 2th, 2024

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